

Lecture 1: Introducing UML for Mobility

Lecture 2: Refining Mobility Designs

- Refining mobility activities
- Refining mobility in sequence diagrams
- [A semantic approach to refinement: Mobile TLA](#)

Lecture 3: Property-driven Development of Mobile Systems

A Semantic Approach to Refinement: Mobile TLA



UML for mobility

- semi-formal graphical notation
- semantics and formal foundation non-obvious
- no notion for reasoning on mobile systems
- no abstract notion of refinement

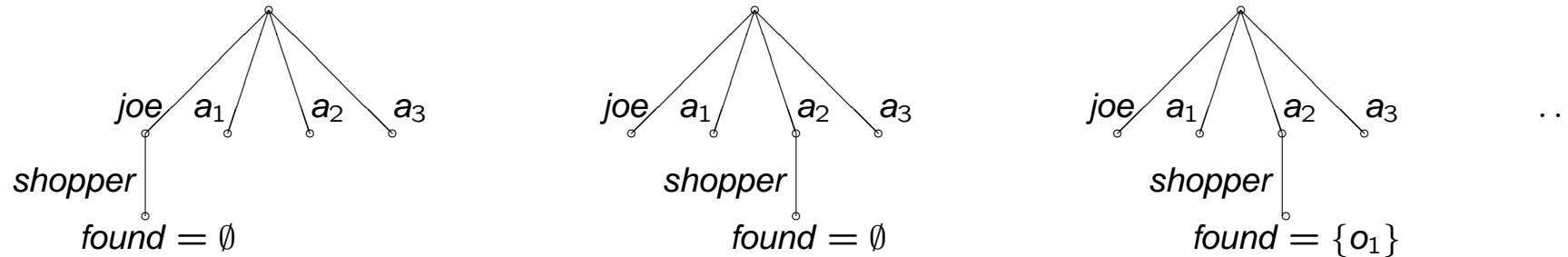
Existing formalisms for mobile systems

- mostly calculi, some with associated logics
- “intensional” semantics, reflecting process structure
- no good notions of refinement

Reactive systems

- transition system semantics (next-state relation + fairness)
- temporal logic properties
- refinement : stuttering invariance

Computational model



Configurations (t, λ)

- t finite tree, edges labelled by unique names
- λ assigns local states to nodes

Computations $\sigma = (t_0, \lambda_0), (t_1, \lambda_1), \dots$

Shopping agent specification (1)

Assume: fixed, finite set Net of names, $joe \in Net$, $shopper \notin Net$

Network topology

$$Topology \equiv \square \bigwedge_{n,m \in Net} n \langle m[\mathbf{false}] \rangle$$

all nodes present at top level

Initial condition

$$Init \equiv \bigwedge joe \langle shopper \langle \mathbf{true} \rangle \rangle \\ \bigwedge shopper [ctl = \text{"idle"}]$$

shopping agent in domain joe ...
... and in "idle" state

Prepare shopper to shop for item x

$$Prepare(x) \equiv \bigwedge shopper \langle \mathbf{true} \rangle \bigwedge \circ shopper \langle \mathbf{true} \rangle \\ \bigwedge shopper [ctl = \text{"idle"}] \\ \bigwedge \circ shopper [ctl = \text{"shopping"}] \\ \bigwedge \circ shopper [target = x \wedge found = \emptyset]$$

shopping is (and stays) here
state changes from "idle" ...
... to "shopping"
initialize $target$ and $found$

Shopping agent specification (2)

Remaining state-changing actions

$GetOffer \equiv \dots$

get an offer and insert into *found*

$PickOffer \equiv \dots$

select among offers in *found*

Move among network nodes

$$Move_{n,m} \equiv \wedge n \langle shopper \langle \mathbf{true} \rangle \rangle$$

$$\wedge shopper[ctl = \text{“shopping”}]$$

$$\wedge n.shopper \gg m.shopper$$

shopping agent is in *n*'s domain
and is in “shopping” state
shopper moves to *m*'s domain,
preserving local state

Overall specification (ignoring fairness)

$$Shopper \equiv \wedge Topology \wedge Init$$

$$\wedge \square [joe[(\exists x : Prepare(x)) \vee PickOffer] \vee \bigvee_{n \in Net} n[GetOffer]]_{vars}$$

$$\wedge \bigwedge_{n \in Net} \square [\bigvee_{m \in Net} Move_{n,m}]_{-n.shopper}$$

Spatial extensions of TLA

Formulas evaluated at run σ and name n

$$\sigma, n \models F$$

Explicit name references

$$m[F]$$

- F holds at location m below ... provided m exists
- Note : m may be arbitrarily deep in subtree

“Everywhere” operator

$$\bar{\square}F$$

F holds at all nodes of the subtree

Structural modification of trees

$$\alpha.n \gg \beta.n$$

- subtree at $\alpha.n$ before transition equals subtree at $\beta.n$ after transition
- local state at moving subtree preserved

The shopping agent is always at some net location

$$\textit{Shopper} \Rightarrow \Box \bigvee_{n \in \textit{Net}} n.\textit{shopper} \langle \mathbf{true} \rangle$$

The shopper idles only at its home location

$$\textit{Shopper} \Rightarrow \Box (\textit{shopper}.ctl = \text{"idle"} \Rightarrow \textit{joe}.\textit{shopper} \langle \mathbf{true} \rangle)$$

Refinement of mobile systems

Operation refinement (Action Refinement)

- decompose high-level operations
- represented by implication (stuttering invariance)

Spatial decomposition (Location Refinement)

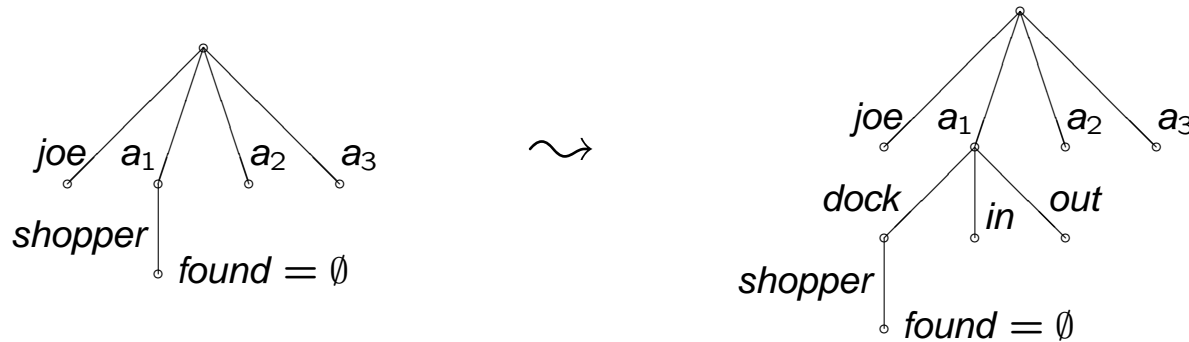
- refine high-level location n into a tree (with root named n)
- in general also distribute local state of n

Virtualisation of locations (Location and Move Refinement)

- implement high-level location n by structurally different hierarchy
- preserve external behavior : n hidden from high-level interface

Spatial decomposition

Suppose visiting agents are kept in a “dock” location



Still conforms to the original specification

- formula *Shopper* doesn't mention locations *dock*, *in*, *out*
- location *shopper* is still below location a_1

Spatial decomposition in detail

Refined initial condition

$$\begin{aligned} \text{DockedInit} \equiv & \wedge \text{joe.dock}_{\text{joe}}.\text{shopper}\langle \mathbf{true} \rangle \\ & \wedge \text{shopper}[\text{ctl} = \text{"idle"}] \end{aligned}$$

shopper still in *joe*'s domain
local state unaffected

Refined move actions

$$\begin{aligned} \text{SendShopper}_n \equiv & \wedge n.\text{dock}_n.\text{shopper}\langle \mathbf{true} \rangle \\ & \wedge \text{shopper}[\text{ctl} = \text{"shopping"}] \\ & \wedge n.\text{dock}_n.\text{shopper} \gg n.\text{out}_n.\text{shopper} \end{aligned}$$

stuttering action at high level

$$\begin{aligned} \text{MoveImpl}_{n,m} \equiv & \wedge n.\text{out}_n.\text{shopper}\langle \mathbf{true} \rangle \\ & \wedge n.\text{out}_n.\text{shopper} \gg m.\text{in}_m.\text{shopper} \end{aligned}$$

specialization of *Move* action

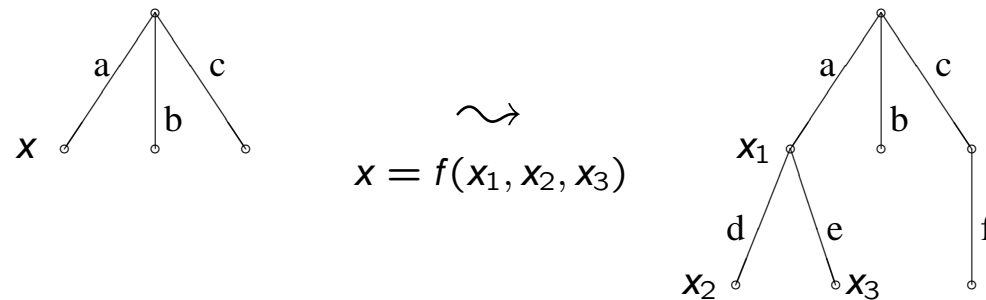
$$\text{RcvShopper}_m \equiv \dots$$

another stuttering transition

The refined specification again implies the original one

Spatial decomposition: general case

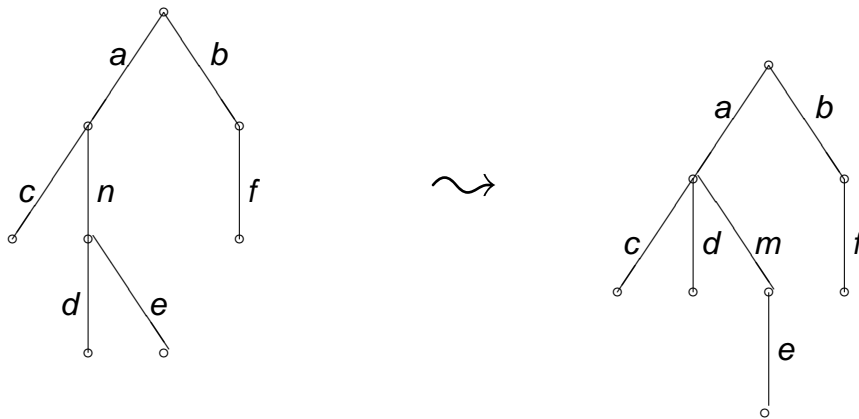
Usually, decomposition requires distribution of state



Refinement is then expressed as $Impl \Rightarrow \exists a.x : Spec$

local state variable x hidden from high-level interface

Modify spatial hierarchy



Location n hidden from interface

$Impl \Rightarrow \exists n : Spec$

preserve external behavior, except for location n

SlowShopper : refine move action

Non-atomic moves across network

$StartMove_n \equiv \wedge n.shopper \langle \mathbf{true} \rangle$ *shopper moves to transit $\notin Net$*
 $\wedge shopper[ctl = \text{"shopping"}]$
 $\wedge n.shopper \gg transit.shopper$

$EndMove_m \equiv \wedge transit.shopper \langle \mathbf{true} \rangle$ *shopper moves to destination*
 $\wedge transit.shopper \gg m.shopper$

Implementation does not imply specification

$\not\models SlowShopper \Rightarrow \square \bigvee_{n \in Net} n.shopper \langle \mathbf{true} \rangle$

Solution : hide *shopper* in original specification

$\models SlowShopper \Rightarrow \exists shopper : Shopper$

Summary

- Simple refinement calculi for activity and sequence diagrams for mobility
- MTLA as a formal basis for a UML notion of refinement: Refinement is implication!

Current Work

- Refinement of other UML diagrams
- Connecting MTLA with UML